

## 1. MOTIVATION

Our goal is to perform anomaly detection in a unique setting, removing the reliance on data and/or temporal assumptions.

Our setting is largely unaddressed in vision-based anomaly detection, but appears often in practice



**First-time data:**  
New systems and environments



**Personalized results:**  
Unique testing distribution

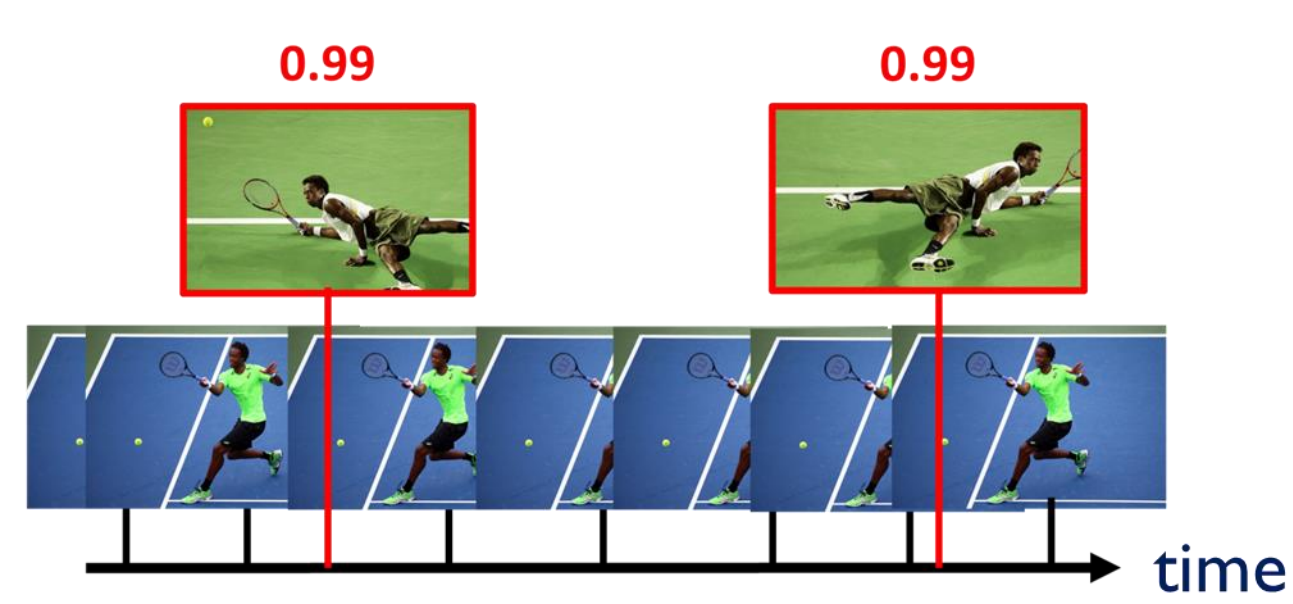
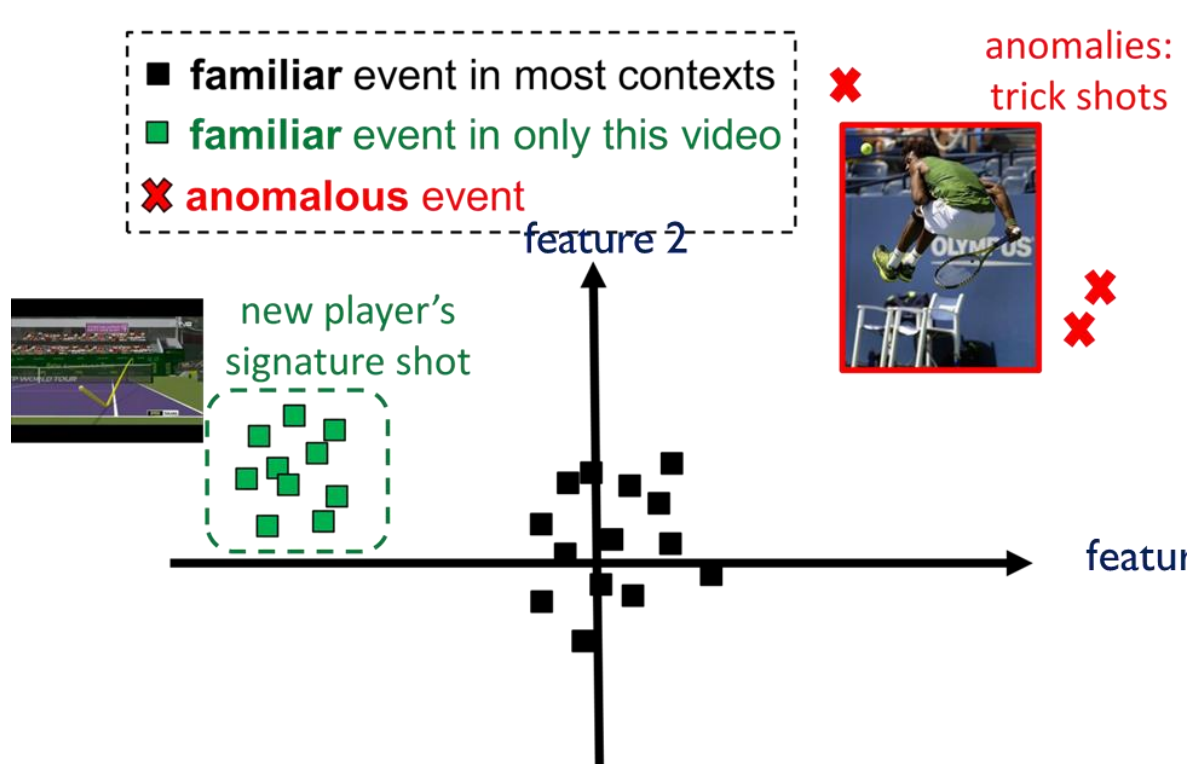


**Database sifting:**  
Exploring a single data chunk

Our setting involves two challenging restrictions

(1) Operate relative to the test sequence

(2) Score independent of ordering

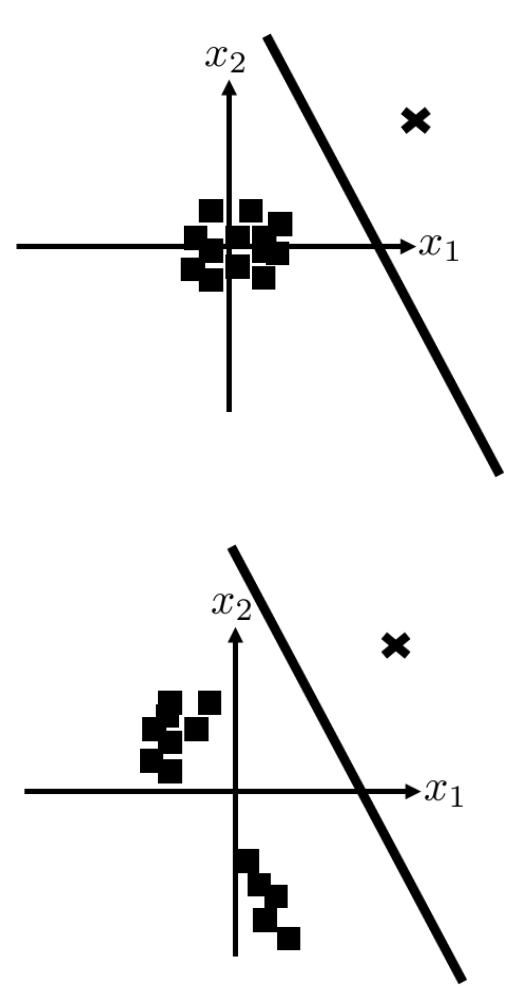


## 2. APPROACH & KEY INSIGHTS

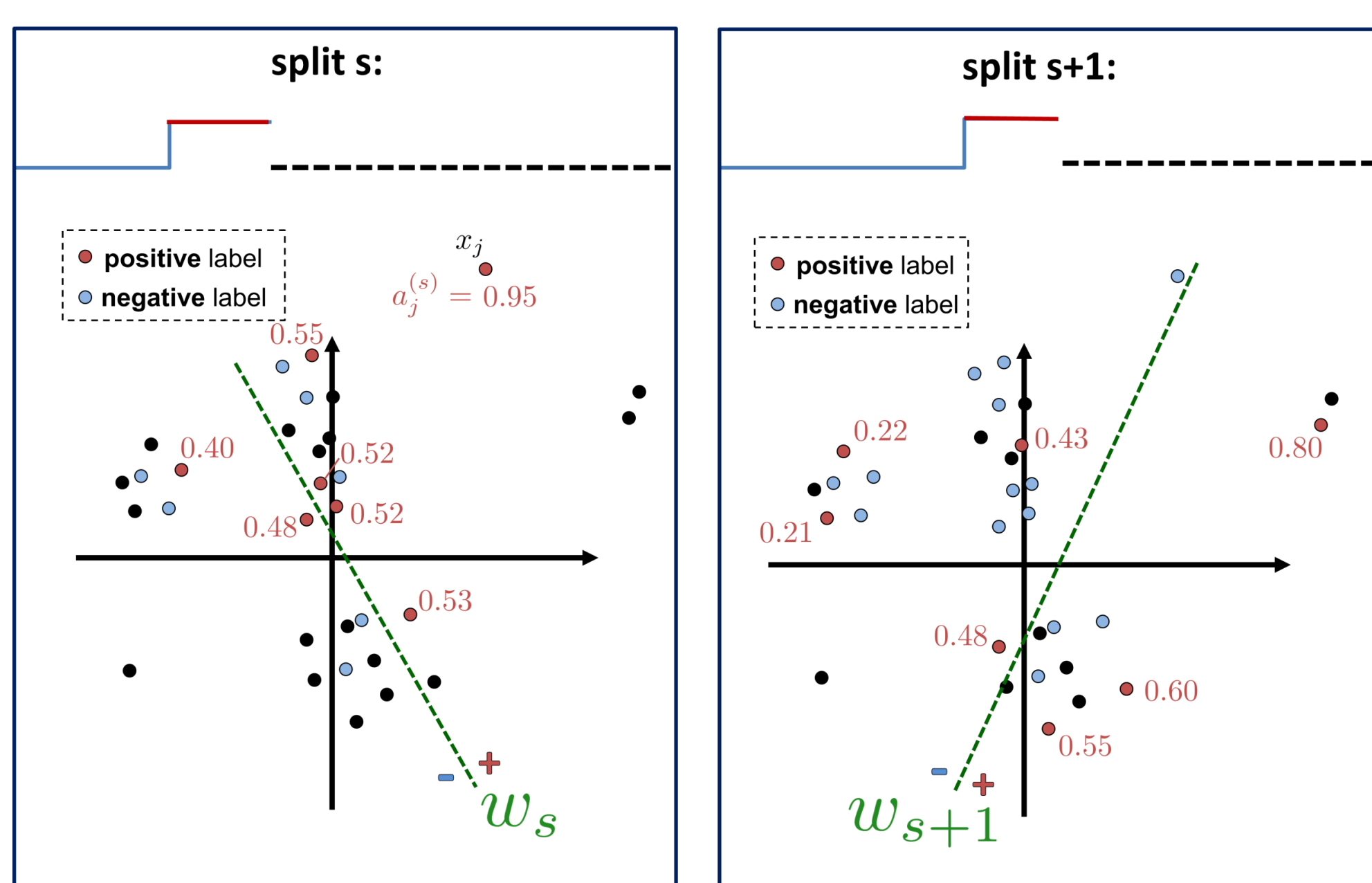
Taking a discriminative, permutation-based approach allows us to operate in this setting

**Insight #1:** Density ratios directly estimate discriminability, minimizing distribution assumptions

Density ratio concept

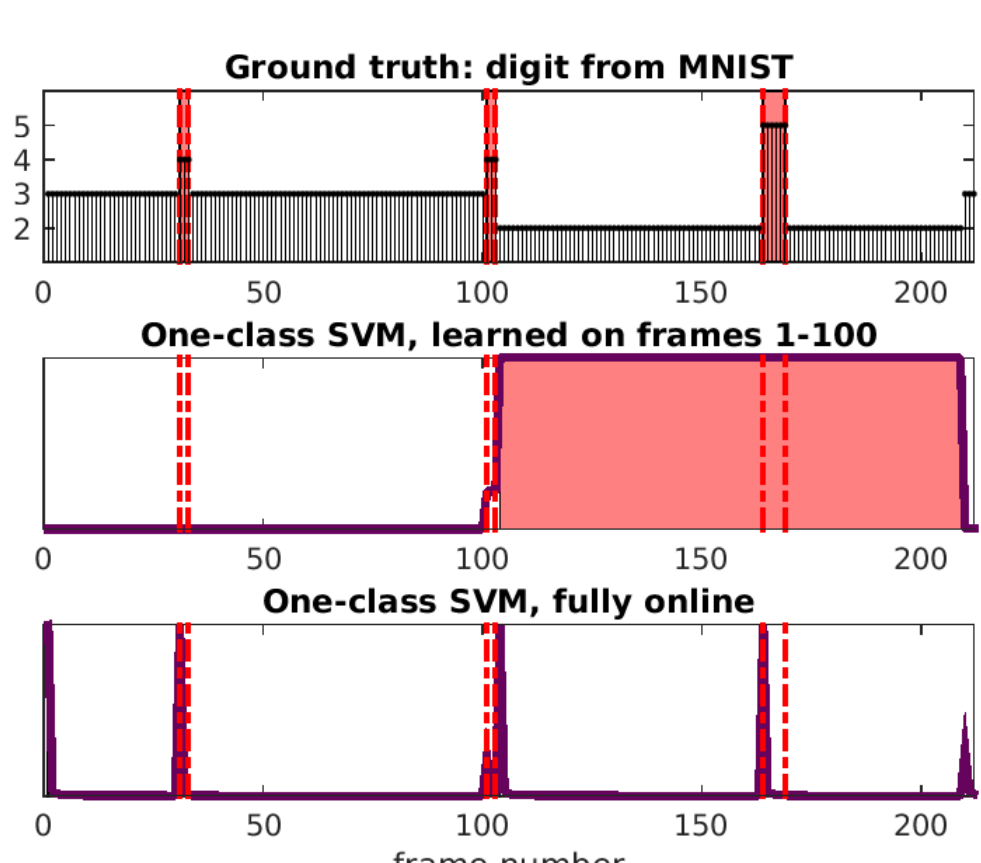


How we use density ratio estimation

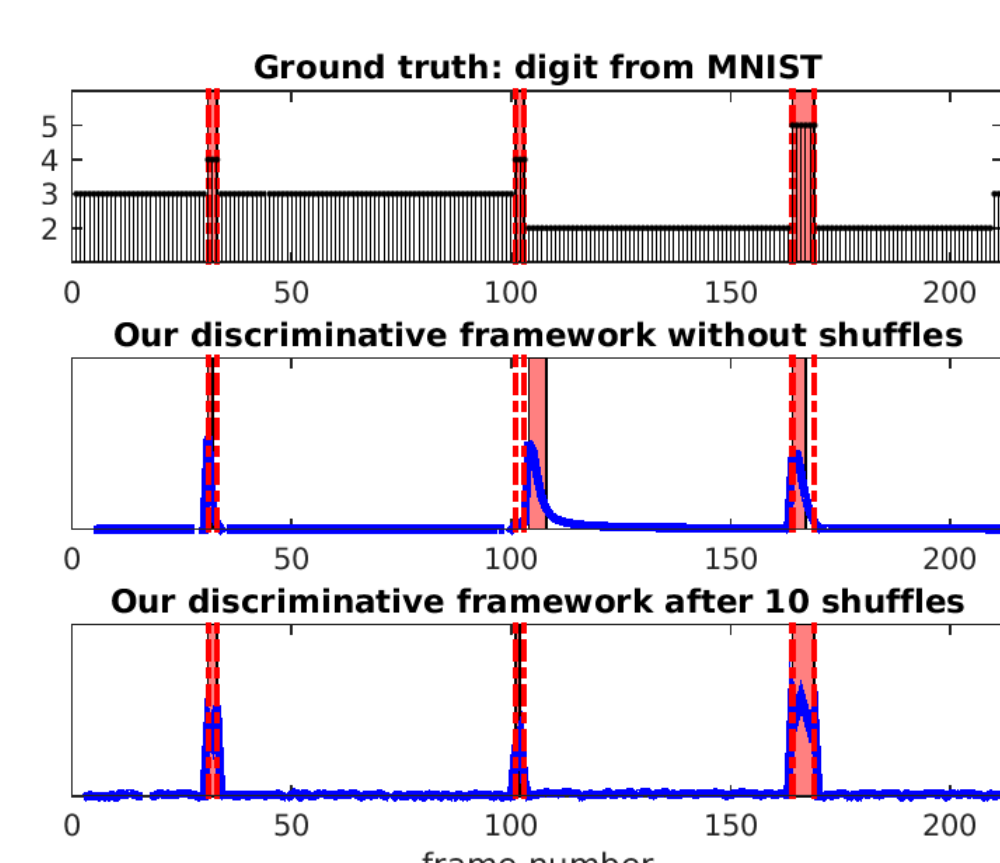


**Insight #2:** Permutation testing removes temporal assumptions, avoiding false positives

Scanning techniques

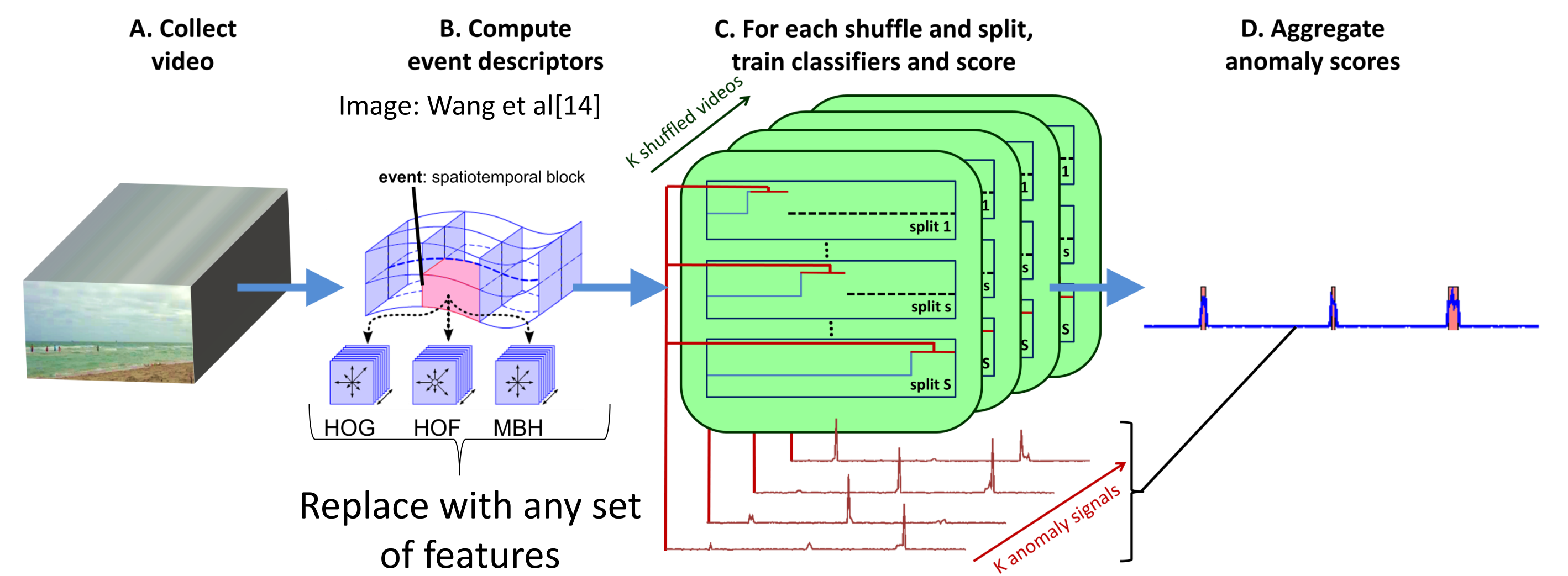


Our method



## 4. SYSTEM OVERVIEW

The framework from video to anomalies

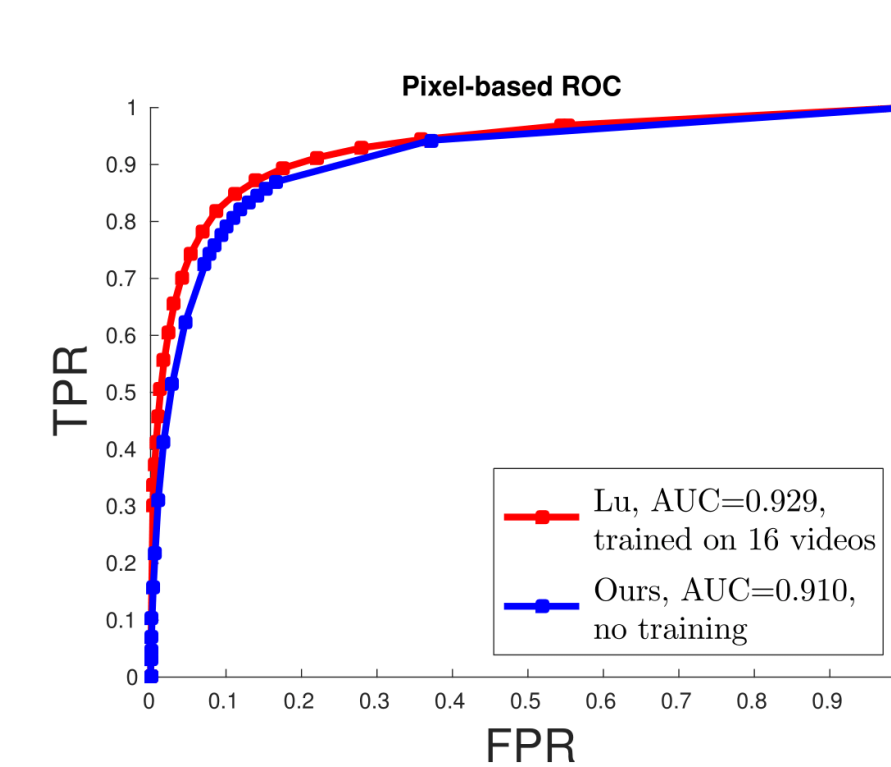


- No training data required
- Anomaly scores are independent of ordering

## 5. RESULTS

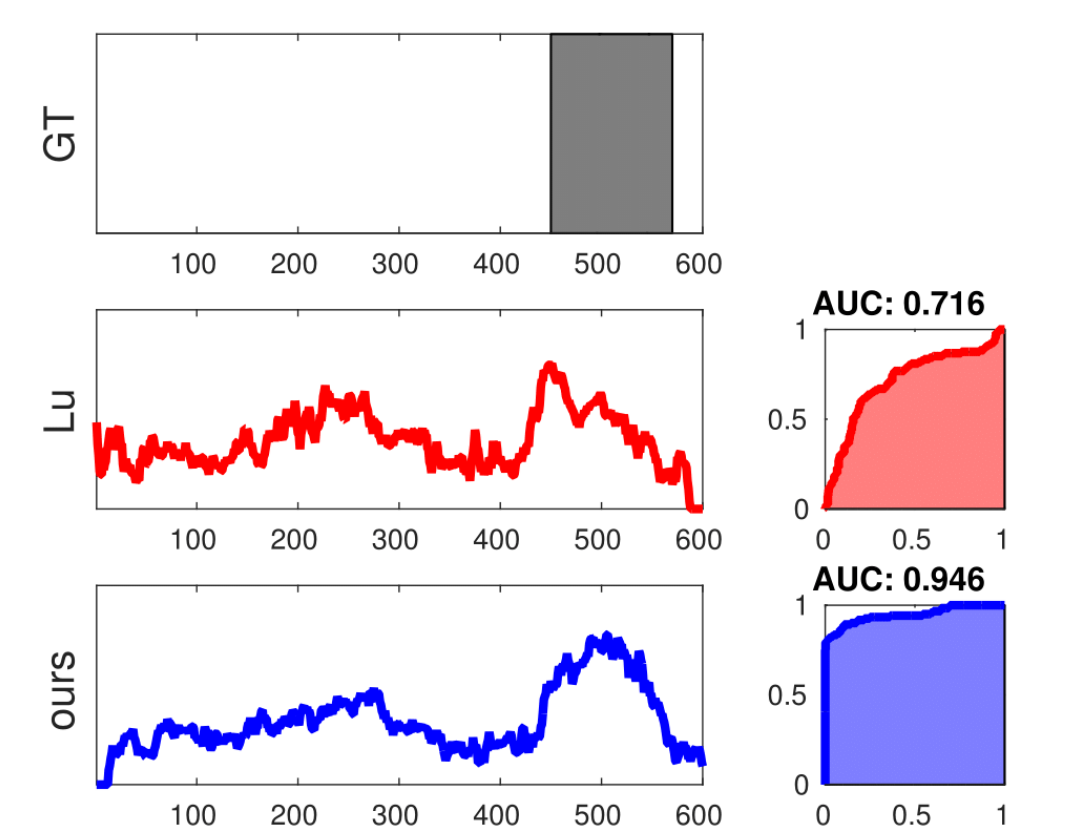
This method performs as well as other methods that require a training set

**Avenue Dataset**  
Similar frame- and pixel-based ROC, without using the training set

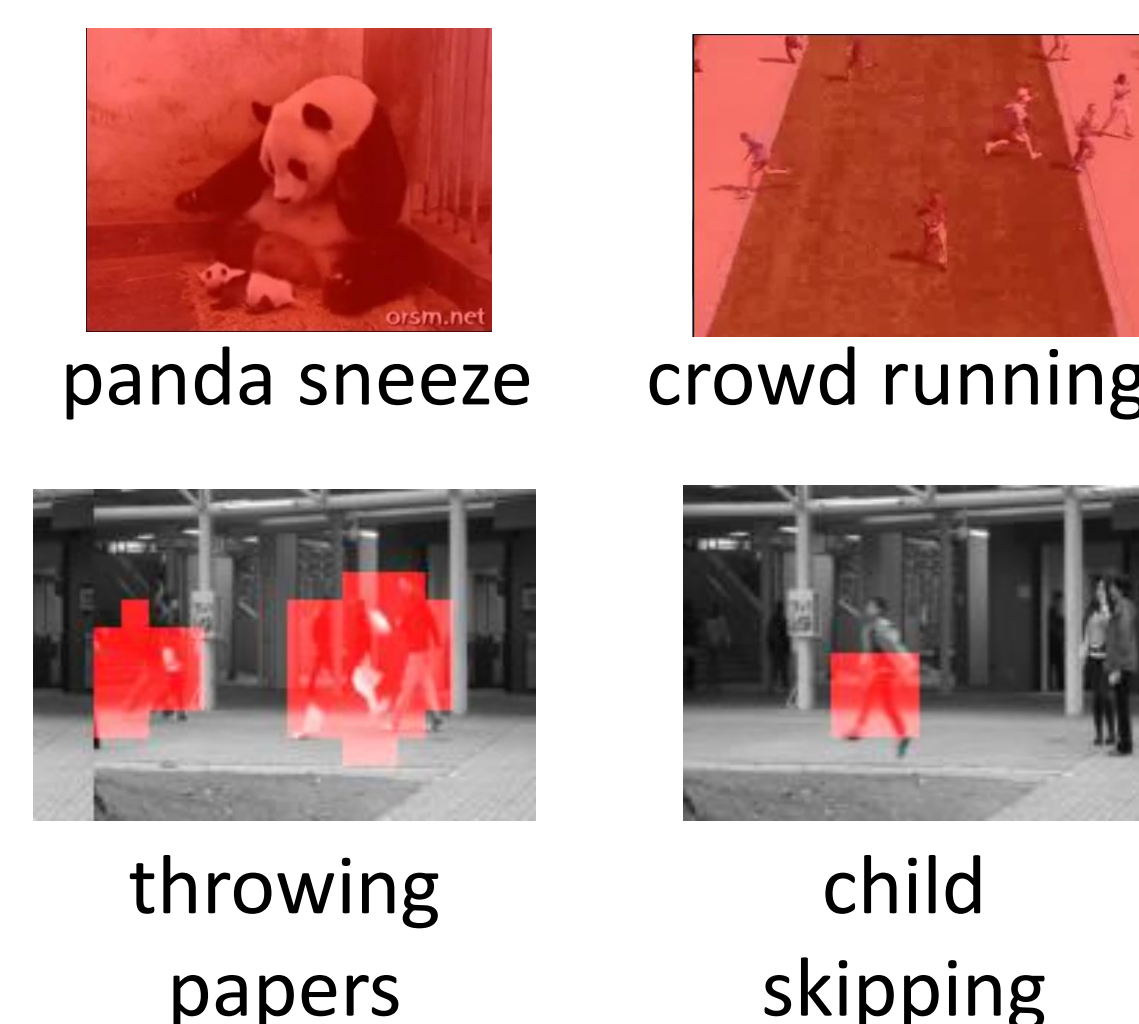


Comparison: Lu, et al. ICCV 2013

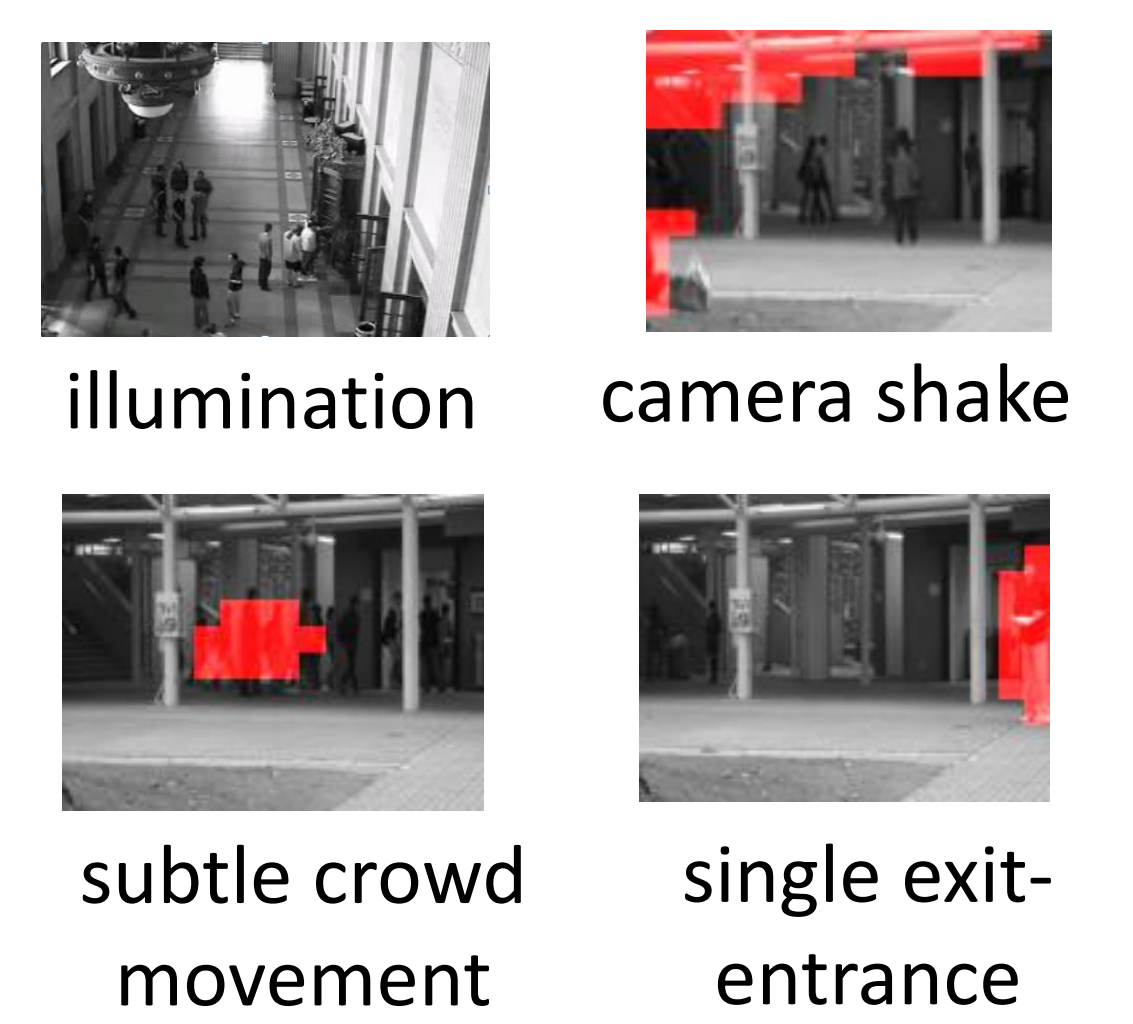
**UMN Dataset**  
Higher AUC on all but 1 scene  
Example: Scene 7



Examples: Correct detections

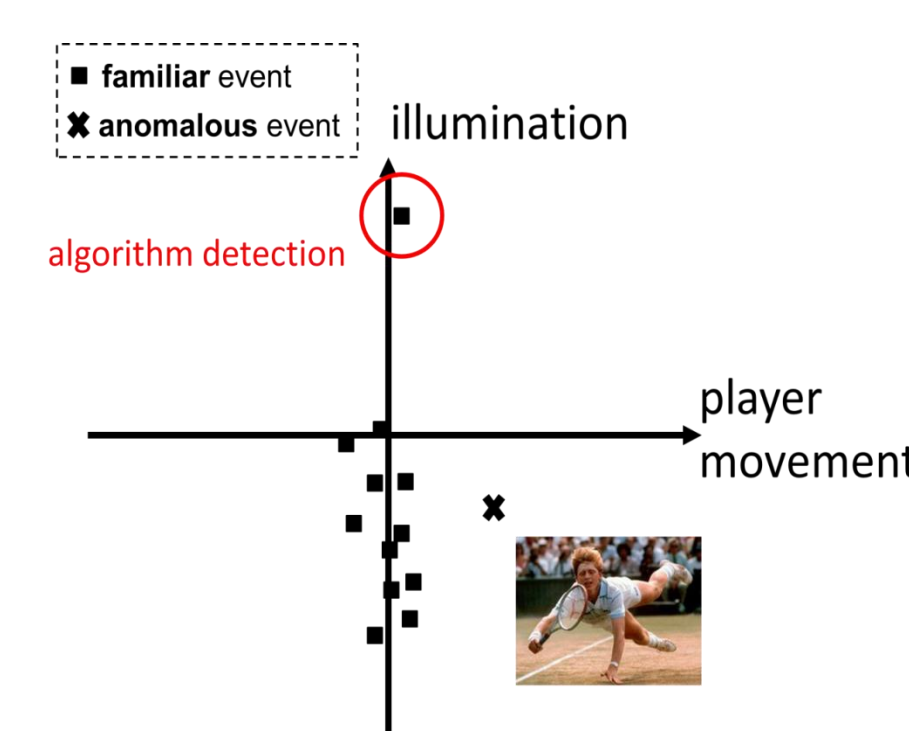


Examples: Failure cases



## 6. FUTURE WORK

Context-driven improvements could come from feature learning, active learning, and data



**Feature learning:**  
align with human notion of abnormality



**Active learning:**  
incorporating feedback from humans



**Datasets:**  
developing larger, more realistic benchmarks

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